



OGC Testbed-14 Machine Learning for Earth Observation (ML/EO)



Final Demonstration meeting
ESA/ESRIN, January 2019

Kevin Heffner, Tom Landry



Agenda



Machine Learning Taxonomy

TB-14 ML/EO Task Overview

TB-14 ML/EO Proof of Concept

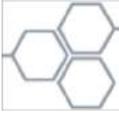
TB-14 ML/EO Deep Learning Applications

TB-14 ML/EO Findings & Recommendations

TB-15 ML Thread

Conclusions

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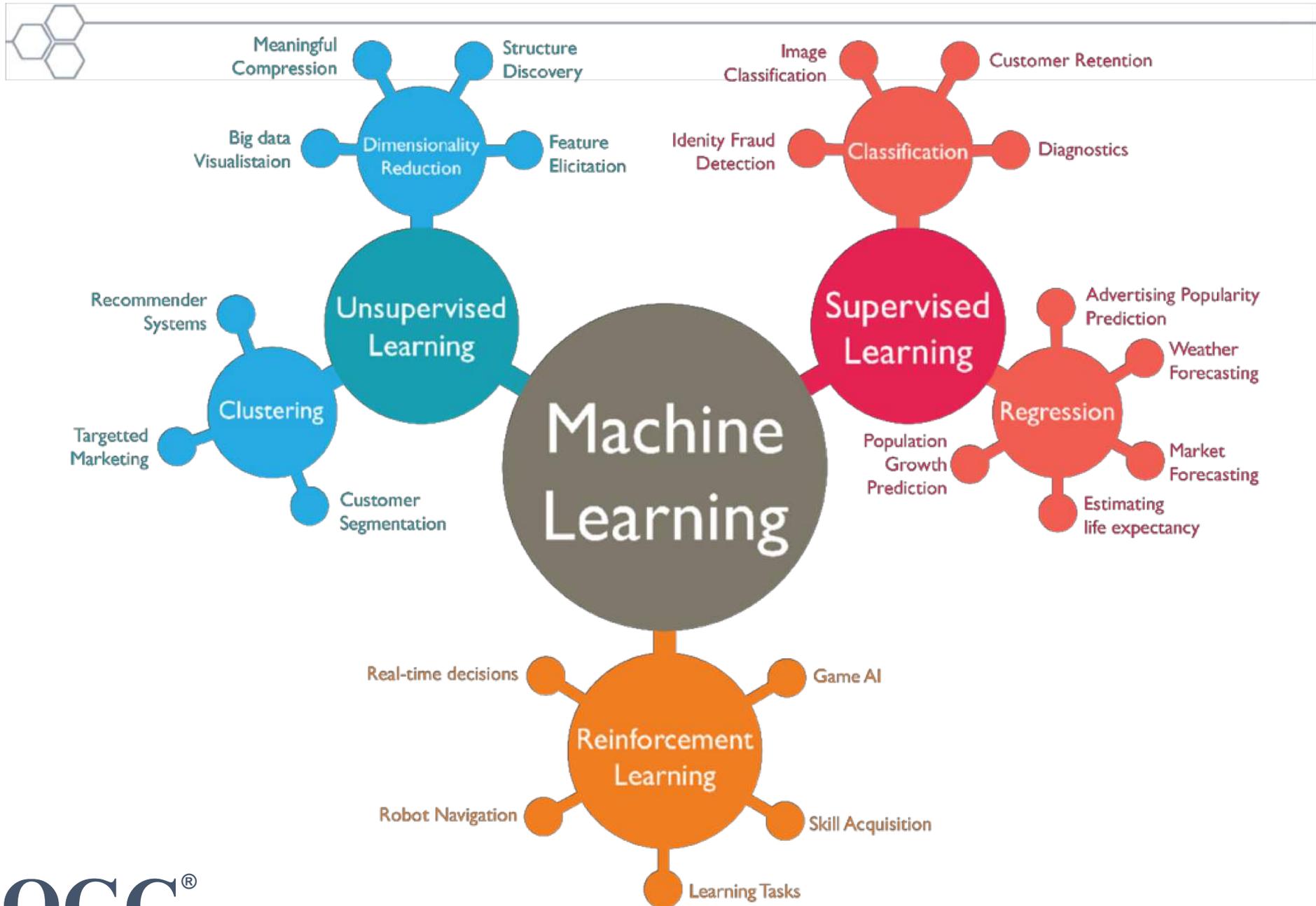
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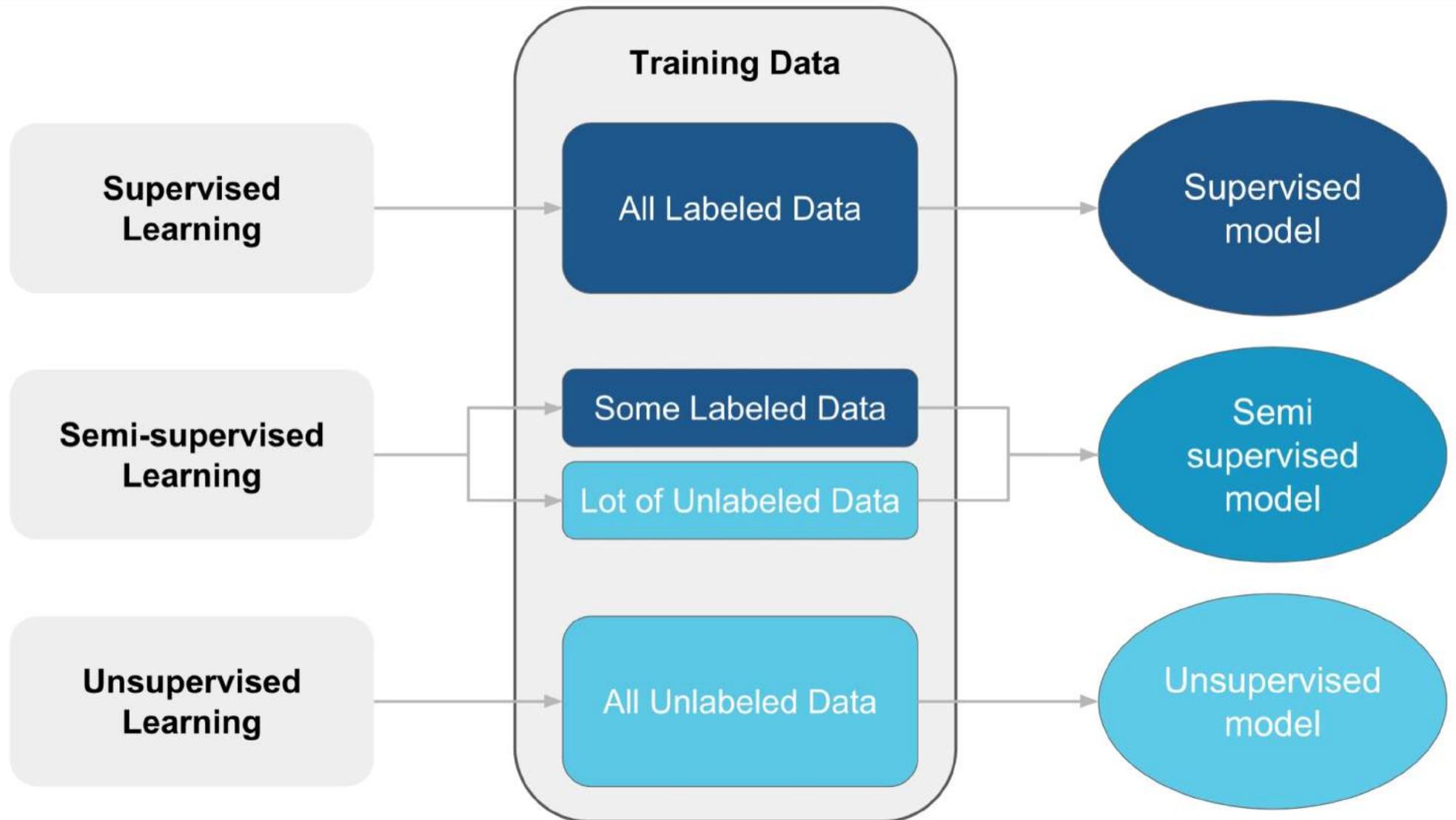
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TAXONOMY OF MACHINE LEARNING



Supervised, Semi-Supervised & Unsupervised ML



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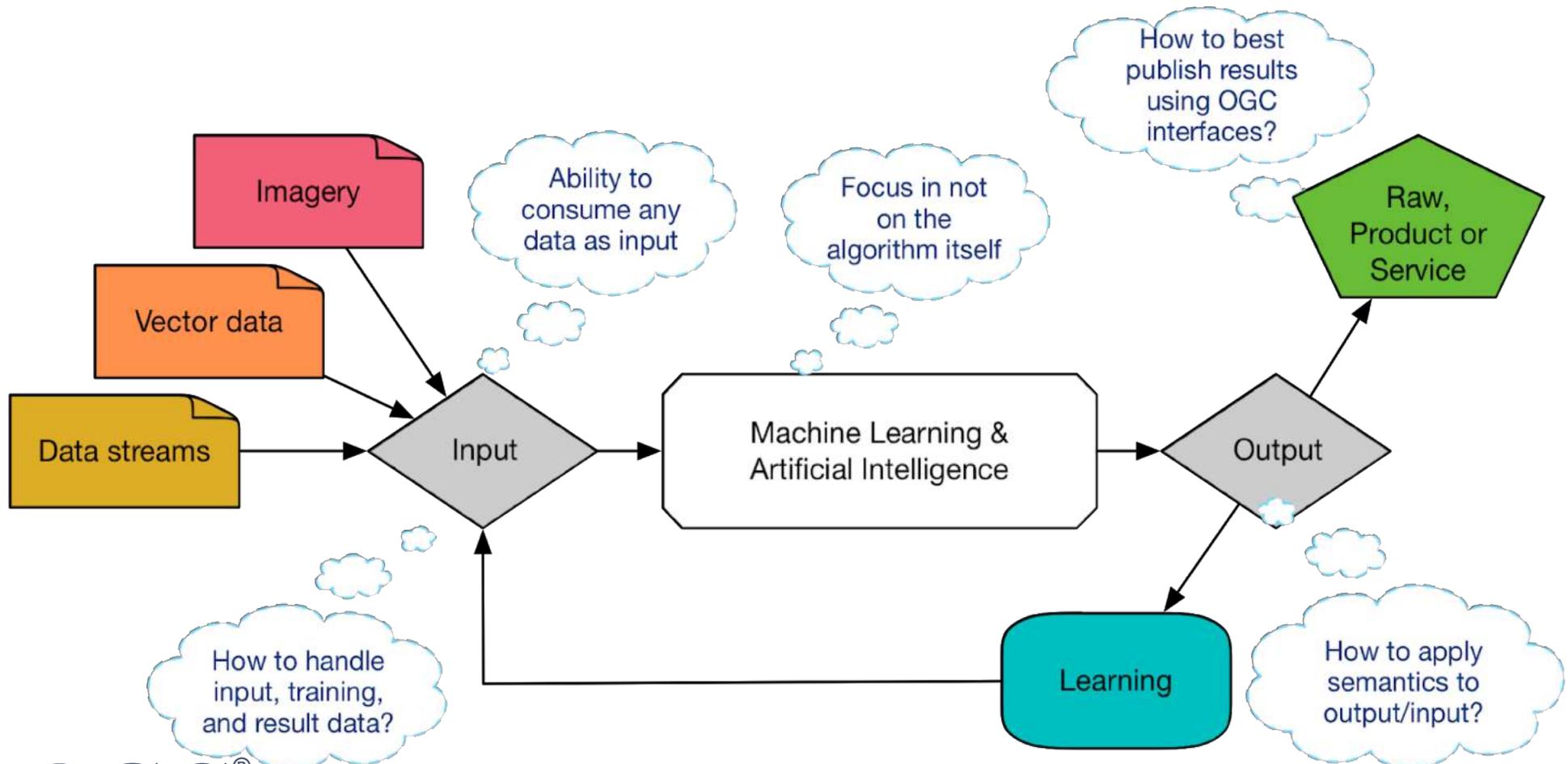
Conclusions

TB-14 ML/EO Task: Motivation

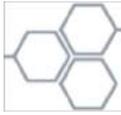


Modeling, Portrayal, and Quality of Service (MoPoQ) Thread

Question: What is best approach to support ML and AI using OWS?



TB-14 ML/EO Task: Participants and sponsors

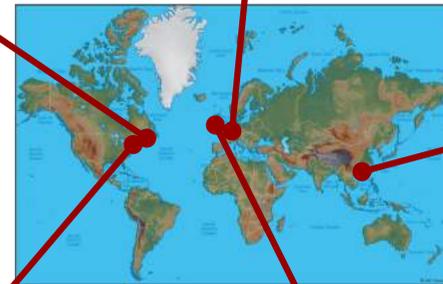


International Effort: NA: CAN, USA EUR: GBR, GER SEA:TWN

Sponsors



Participants



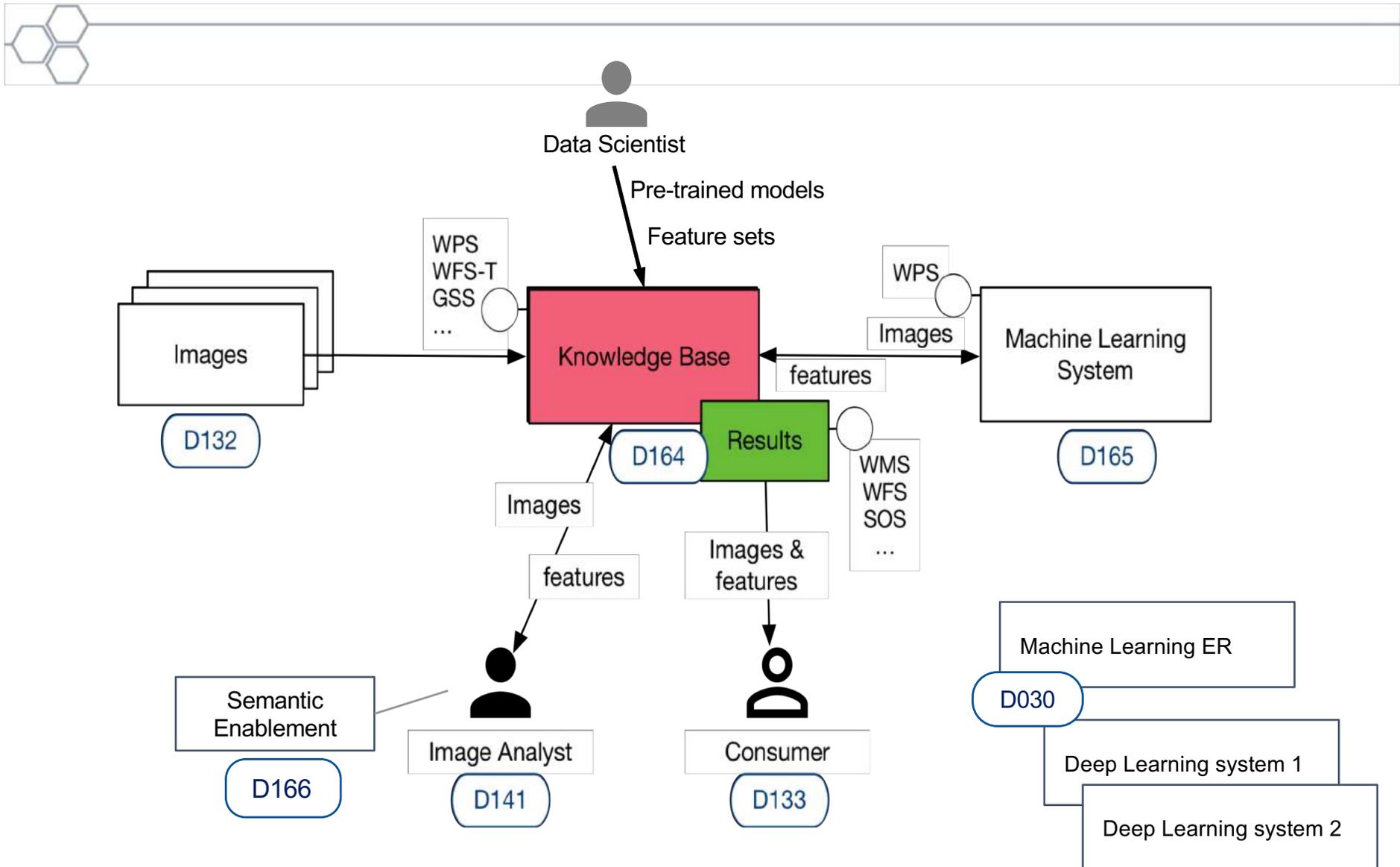
Tom Landry, *CRIM*
Martin Sotir, *CRIM*
Cullen Rombach, *Image Matters*

Cameron Brown, *Envitia*
Neil Kirk, *Envitia*
Benjamin Pross, *52 North*

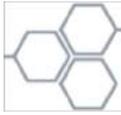
Chih-Wei Kuan, *Feng Chia University*



TB-14 ML/EO Task: Architecture



TB-14 ML/EO Task: Deliverables



D030: Machine Learning ER

D132: Image repository and feature store

D133: Client to Knowledge Base (KB)

D141: Machine Learning (ML) validation client

D164: ML Knowledge Base

D165: ML System (MLS)

D166: Semantic Enablement of ML (*not in CFP*)

TB-14 ML/EO Task: Summary of Use cases

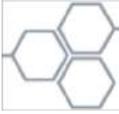


Image Analyst

- **Annotates** images, i.e. links new features to classes
- **Trains** new model using annotated images
- **Validates** model output; re-trains model, if necessary

Consumer

- **Executes** MLS on geospatial data (with trained, validated model)
- **Consults** MLS outputs: images and features

Data Scientist (*Not in original CFP*)

- **Provides** pre-trained models from their own training feature sets
- **Packages** reference MLS and data samples

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TB-14 ML/EO POC: Classification

ENVITIA HORIZON

Search for location by name or reference within Current View

Classified
tb14:IMG_PHR1B_P_201509271105571_ORT_1974032101-001_R1C1_subset

Source Image

Opacity:

EJS2 Base Map

Show Legend

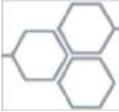
Model Quality

Classify

EPSG: 3857
500 m
1:25000

NOT FOR NAVIGATION OR TARGETING

TB-14 ML/EO POC: Controlled Vocabulary Manager



D166 Semantic Enablement

- Combination of NIEM and NSG
- Land cover classes vs targets

```
{
  "results": [
    {
      "id": "4d2fda7b59b1092b2b028f8ddb3d2e01",
      "uri":
"http://api.nsgreg.nga.mil/codelist/ConveyanceType/automobile",
      "type": [
        "individual",
        "concept"
      ],
      "primary": false,
      "prefix": "codelist",
      "version": "1.0",
      "label": "automobile",
      "description": "Definition: A motor vehicle generally with four
wheels that carries a small number of passengers. Description: [None
Specified]",
      "namespace": "http://api.nsgreg.nga.mil/codelist/ConveyanceType/",
      "localName": "automobile",
      "qname": "codelist:automobile",
      "category": [
        "Individual",
        "additionalProperties"
      ]
    }
  ]
}
```

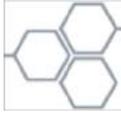
TB-14 ML/EO POC: Validation and Re-training

The screenshot displays the ENVTIA HORIZON web application interface. The top navigation bar includes the ENVTIA HORIZON logo, a search bar, and utility icons for Help, Print, RFI, and Share. The left sidebar shows a 'Model Feature' dropdown set to 'EJS2 Base Map' and a 'Show Legend' button. The main map area shows a satellite view of Paris with several annotations:

- Annotation 1:** A purple box highlights the 'Select Model to Retrain' dropdown menu, which is set to 'MD15432210343433398a'.
- Annotation 2:** A purple box highlights a yellow-shaded area on the map, labeled '2', which is an area of water incorrectly classified as a 'way'.
- Annotation 3:** A purple box highlights the 'Select feature value' dropdown menu, which is set to 'water'. Below this menu are 'Save' and 'Cancel' buttons, and a large green 'Re Train' button.

At the bottom of the map, there is a scale bar (1:10000), a coordinate display (48.8600° Lat, 2.3161° Lon), and a warning: 'NOT FOR NAVIGATION OR TARGETING'.

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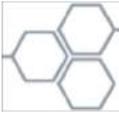
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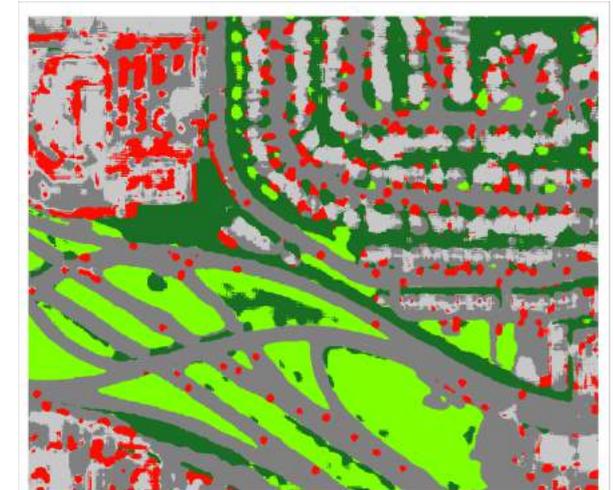
TB-15 ML Thread

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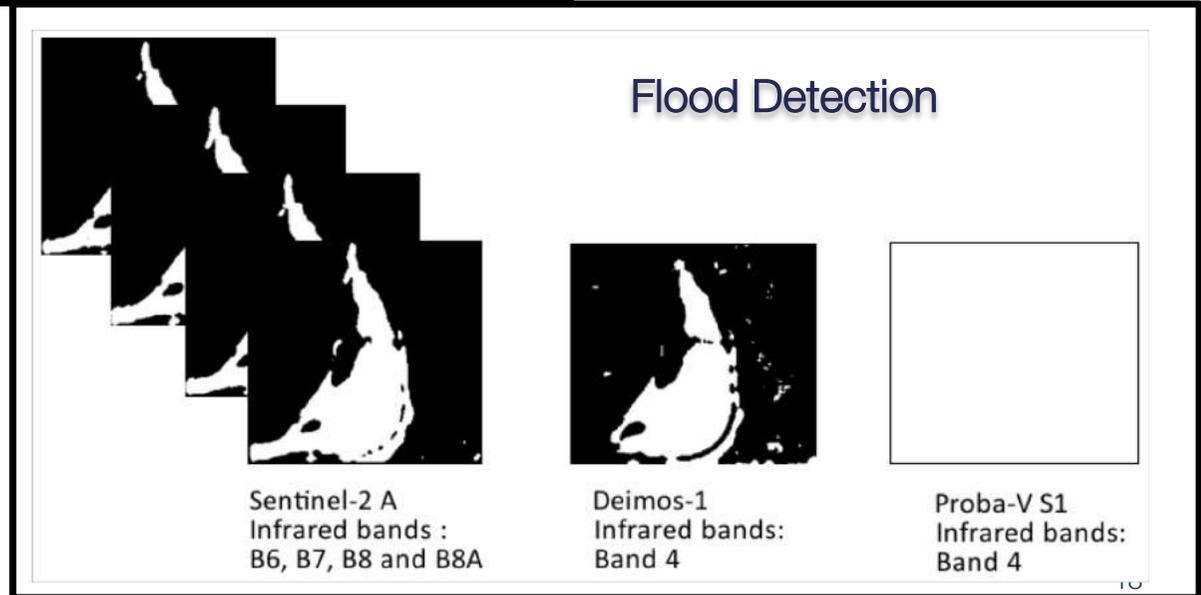
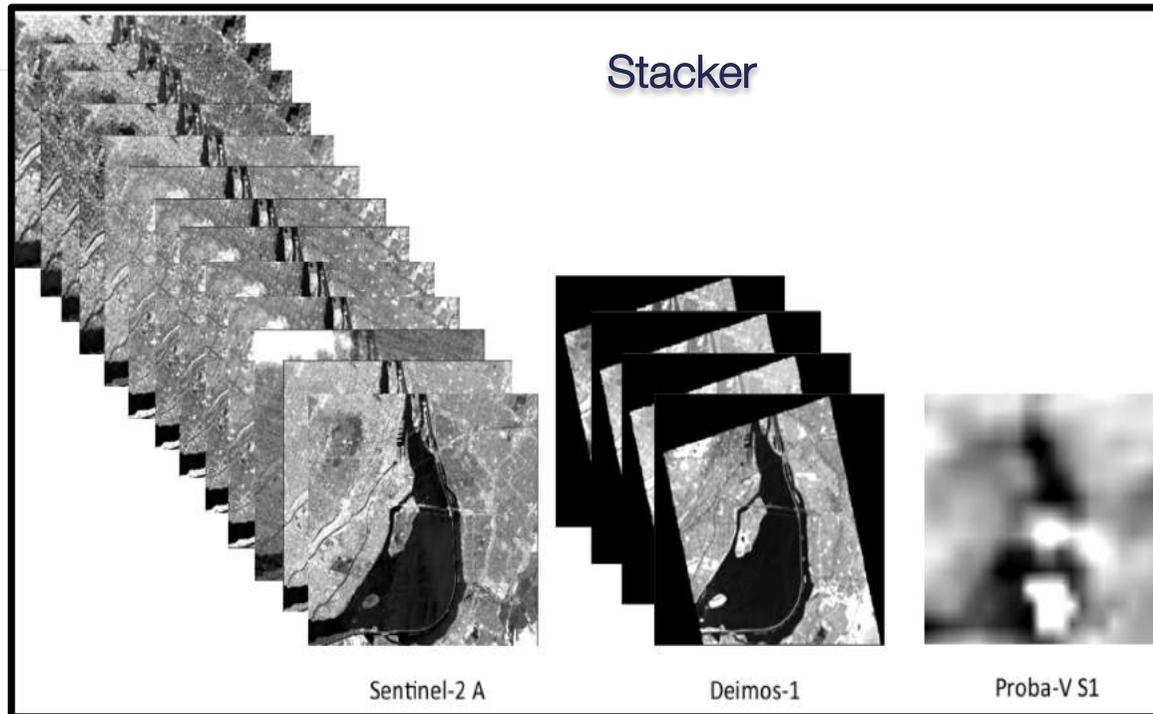
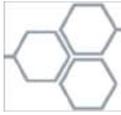
TB-14 ML/EO Task DL Apps: Car Detector



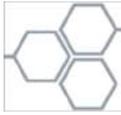
- **5 classes**
 - cars, trees, roads, houses, buildings
 - probability for each class at each px
- **Small training set in Vancouver**
 - about 1000 points per class
- **MLS as standalone Docker**
 - Based on PyTorch
 - Easy to use in CWL workflows
 - Still need vectorization of detections



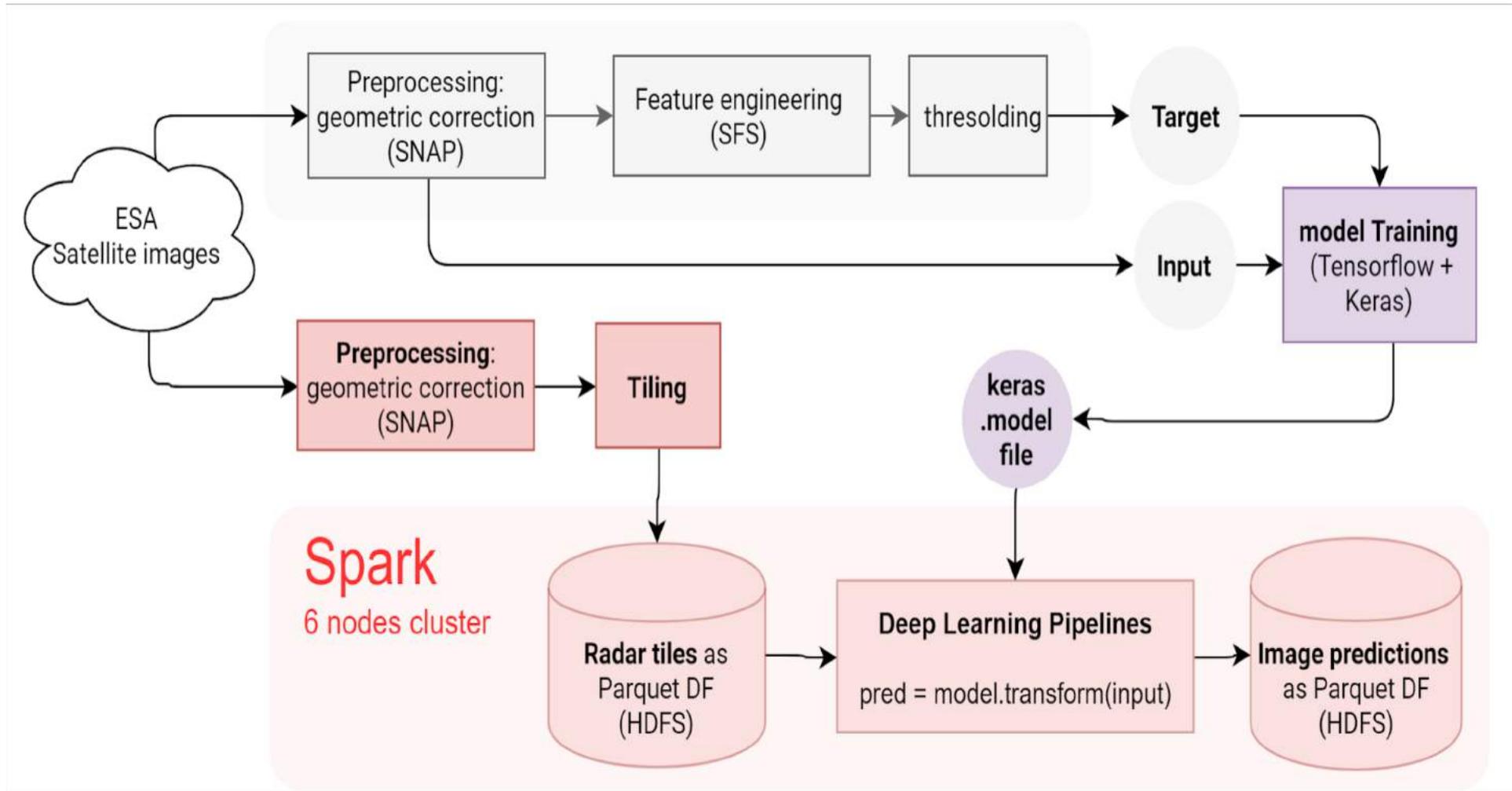
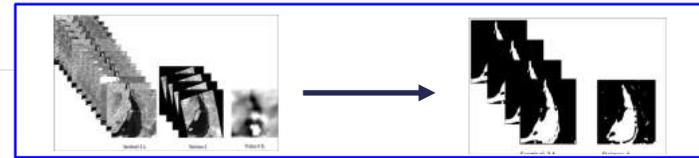
TB-14 ML/EO Task DL Apps: Flood Detection



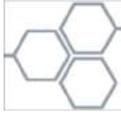
TB-14 ML/EO Task DL Apps: Flood Detection



WORKFLOW DESCRIPTION



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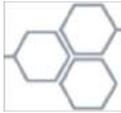
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TB-14 ML/EO: Findings & Recommendations



- **Opportunities**
 - Relatively few standards found in AI and ML
 - ML applications often built as workflows (pipelines, graphs)
 - Models should be discoverable, like applications and data
- **Recommended Standards, Specifications & Extensions**
 - WPS-T 2.0 REST/JSON for specifying processes
 - WFS 3.0 for management of features
 - CSW for Knowledge Base and Controlled Vocabulary Manager
 - CSW-ISO 19115 and CSW-ebRIM application profiles
- **Suggested Future Work**
 - Tasks
 - Temporal, semantic and computational enablements
 - Use of CSW and NextGen services
 - Deliverables
 - Application packages and workflows, Point clouds

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TB-15: ML Thread



Scenarios

- Cloud-free mosaicing, land cover classification
- Forest supply management
- Lake-river differentiation
- Linked data harvest
- Web service discovery

Data: Optical Imagery, LiDAR, Annotated Data, Road & Hydro Networks, DEM, Places, Ontologies, etc.

Standards: WPS, WFS, CSW, WCS, WMS

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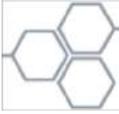


- **TB-14 ML/OE was a challenging, complex task !**
 - Many topics, concerns & deliverables
 - Difficult to converge on design early on
- **Achievements**
 - The disaster use case helped convey the potential value of the work
 - Successfully developed a functional Proof-Of-Concept
 - Good synergy from a diverse group of participants
- **Bottom Line**
 - TB-14 ML provides a good foundation for future work
 - ML now is a first class thread in TB-15
 - Good value delivered to sponsors

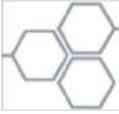


Thank you for your attention !

BACKUP SLIDES

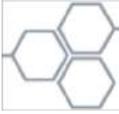


Concept: POC operations



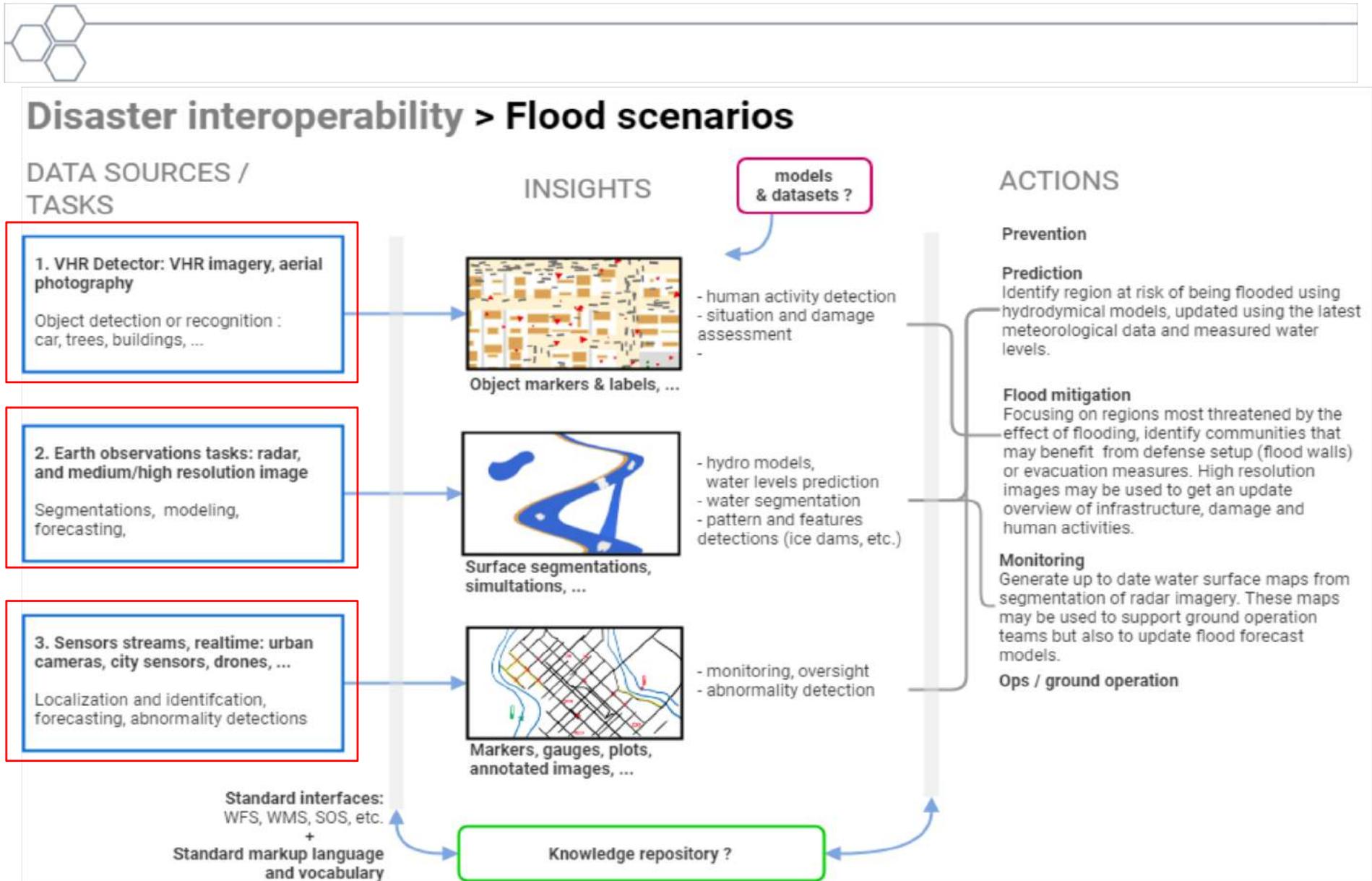
- WCS GetCapabilities, GetCoverage, DescribeCoverage
- WFS GetCapabilities, GetFeature, Update/Delete/Insert
- WMS GetMap
- WPS Execute
 - TrainML, RetrainML, ExecuteML
- ML Knowledge Base (KB). OpenAPI to Get/Store:
 - Models, Images, Features, Metadata
- Controlled Vocabulary Manager (CVM). Search by:
 - Id, uri, namespace, prefix, facet

ML/EO Task: ER by the numbers

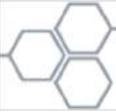


- International effort
 - 5 participating institutions, 3 sponsors. Total 6 countries.
- 230 commits on GitHub, 9 contributors, 9 versions
- 79 pages in 9 sections
- 6 normative documents referenced
- 22 figures, 32 citations
- Recommended future work
 - 5 tasks
 - 9 deliverables
 - 3 ER
- Covers 6 deliverables
 - Plus 2 supporting Deep Learning contributions

Concept: disaster scenario

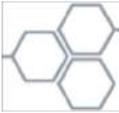


Metadata for DL system



```
check_point = {}
check_point['state_dict'] = model.state_dict() # weights
check_point['model_config'] = self.model_config # informations about the
architectures
check_point['config'] = config # Training configuration
check_point['epoch'] = current_epoch # Training epoch
check_point['iteration'] = current_iteration # Training iteration
check_point['accuracy'] = current_accuracy # Accuracy
check_point['optimizer_state_dict'] = self.optimizer.state_dict() #
optimizer params
check_point['criterion_config'] = self.criterion_config # cost function
check_point['optimizer_config'] = self.optimizer_config # optimizer def
```

GML application schema

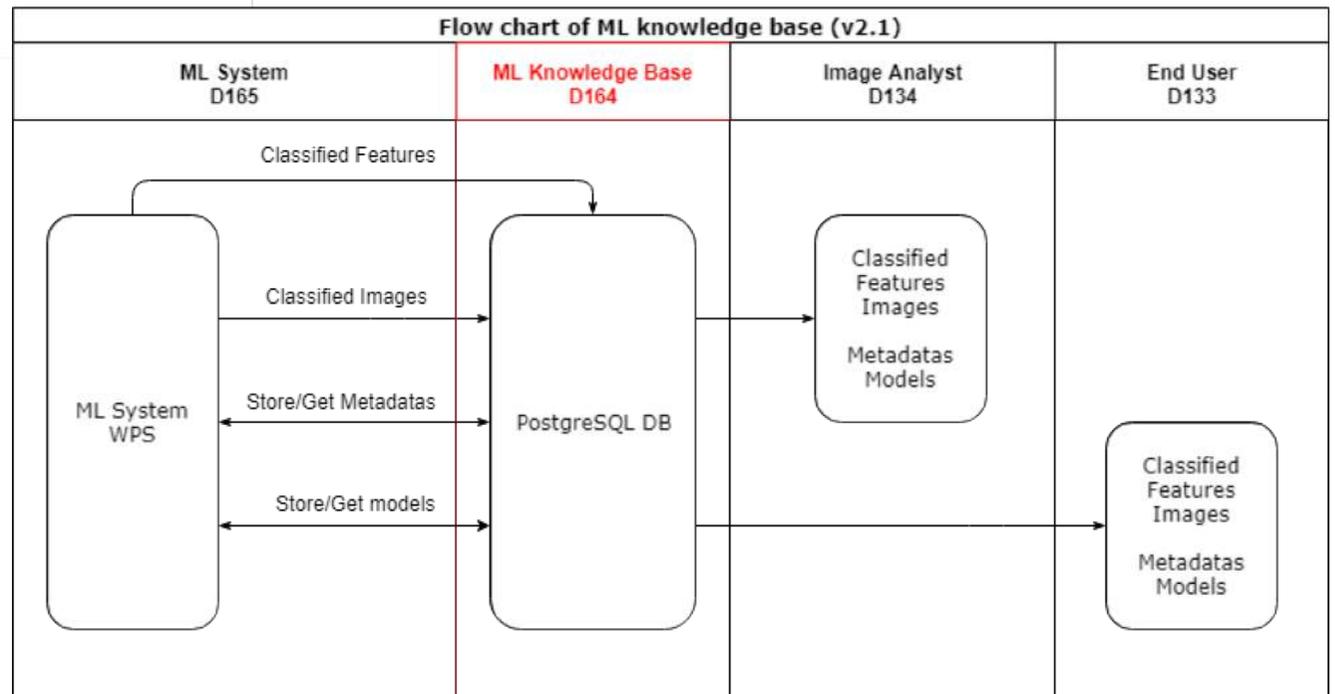
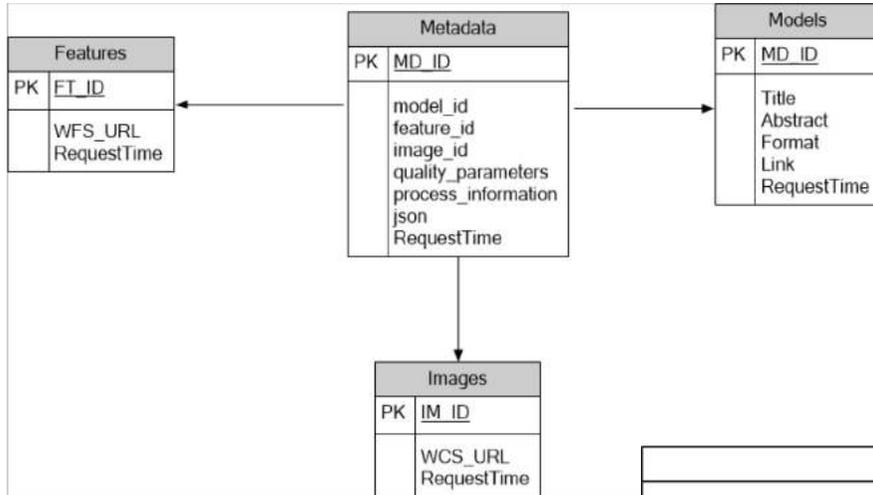


```
<xs:schema xmlns:xs="http://www.w3.org/2001/XMLSchema" xmlns:ogc-tb14-ml="
"http://schemas.opengis.net/testbed14/machine-learning" xmlns:gml="
"http://www.opengis.net/gml/3.2" targetNamespace="
"http://schemas.opengis.net/testbed14/machine-learning" elementFormDefault="
"qualified">
  <xs:import namespace="http://www.opengis.net/gml/3.2" schemaLocation="
"http://schemas.opengis.net/gml/3.2.1/gml.xsd"/>

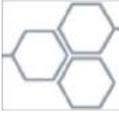
  <xs:element name="ClassifiedFeature" type="ogc-tb14-
ml:ClassifiedFeatureType" substitutionGroup="gml:AbstractFeature">
    <xs:annotation>
      <xs:documentation>A feature representing a real-world object that
has been classified by a Machine Learning image classification
algorithm.</xs:documentation>
    </xs:annotation>
  </xs:element>

  <xs:complexType name="ClassifiedFeatureType">
    <xs:complexContent>
      <xs:extension base="gml:AbstractFeatureType">
        <xs:sequence>
          <!-- The feature identifier in the Feature Store. -->
          <xs:element name="Id" type="xs:long"/>
          <!-- The image classification category, ideally from a
controlled vocabulary such as the NAS or NIEM. -->
          <!-- Implemented here as xs:string for simplicity. Could
use dedicated GML property for codelists instead. -->
          <!-- Similar to properties tb14:category and tb14:term on
tb14:labels feature type in current Feature Store WFS. -->
          <xs:element name="classificationType" type="xs:string"/>
          <!-- The geometric footprint of the feature. -->
          <xs:element name="the_geom" type="
gml:GeometryPropertyType"/>
        </xs:sequence>
      </xs:extension>
    </xs:complexContent>
  </xs:complexType>
</xs:schema>
```

KB database and sequences



Findings: other OGC standards, extensions



- Application Packaging best practices for systems
- Workflow best practices
- WPS, WMS and WFS experiments
 - model interop and transparency
- WMTS and Vector Tiles as inputs to ML systems
- Open Modelling Interface (OpenMI)