

# Janet Fredericks

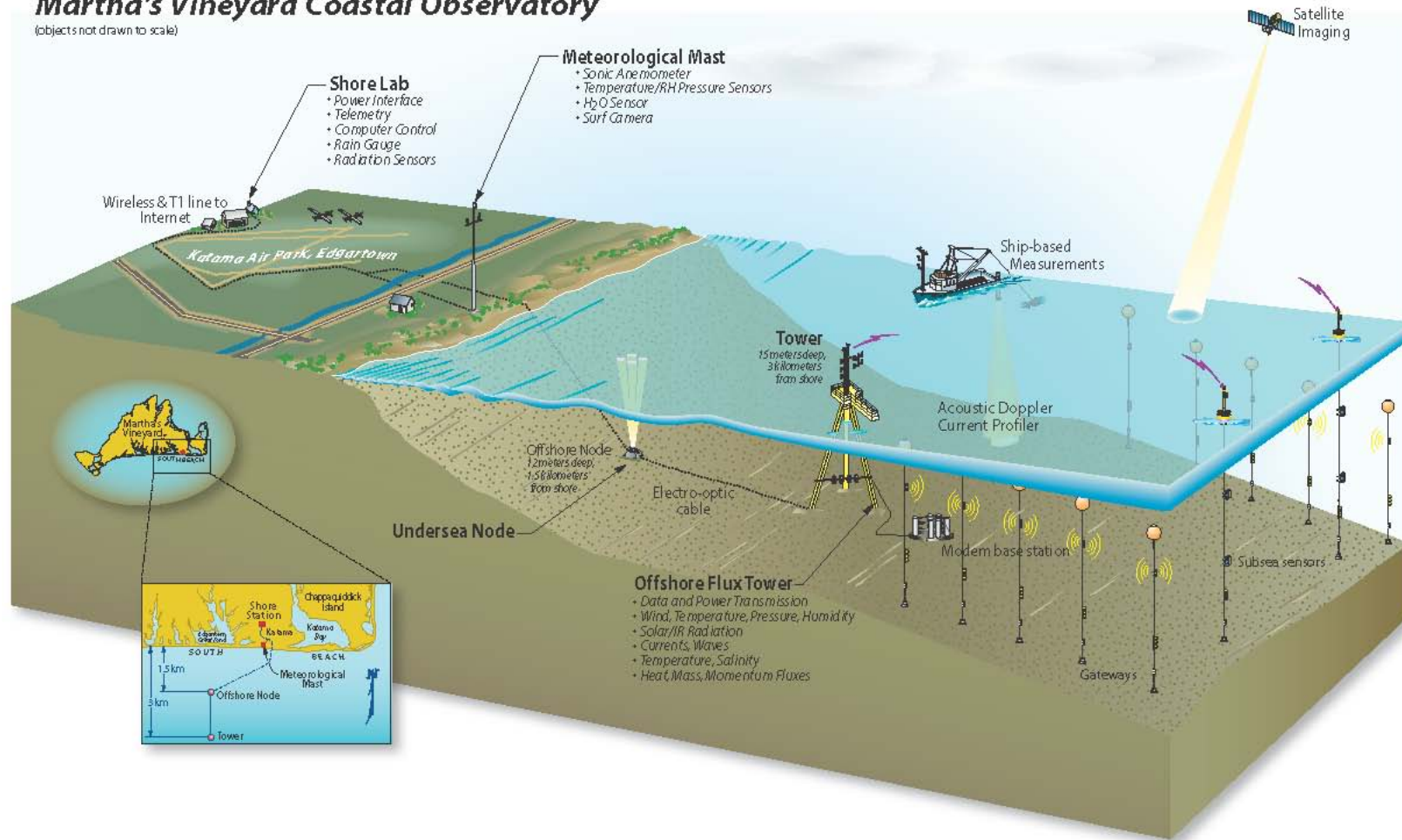
Woods Hole Oceanographic Institution  
Martha's Vineyard Coastal Observatory

Chief Scientist: Dr. Heidi Sosik  
COSMOS: Dr. John Trowbridge  
GEOOS Sensor Workshop  
Geneva – May 2008



# Martha's Vineyard Coastal Observatory

(objects not drawn to scale)



# Ocean Science Interoperability Experiment

The screenshot shows a Mozilla Firefox browser window with the address bar set to <http://www.opengeospatial.org/projects/initiatives/oceansie>. The page title is "Ocean Science Interoperability Experiment | OGC® - Mozilla Firefox". The browser's menu bar includes "Bookmarks", "Tools", and "Help". The address bar has a "Go" button and a search icon. The page content is organized into a header with navigation links: "OGC® Home", "OGC Network™", "OGC User™", and "OGC Forum". Below this is a search bar and a "Search" button. The main content area is titled "Ocean Science Interoperability Experiment" and includes a "Summary" section, "Initiator Organizations", a "Description", and a "Background" section. The "Summary" section states that the experiment will consolidate the Ocean-Observing community's understanding of OGC specifications, solidify demonstrations, and produce a candidate OGC Best Practices document. The "Initiator Organizations" section lists five organizations: Southeastern Universities Research Association (SURA), Texas A&M University Academy for Advanced Telecommunications (TAMU), National Center for Atmospheric Research (NCAR), The Monterey Bay Aquarium Research Institute (MBARI), and Gulf of Maine Ocean Observing System (GoMOOS). The "Description" section explains that the Ocean IE will advance the understanding and application of OGC specifications in web services for interoperable ocean science. The "Background" section describes a workshop in Baltimore in October 2005, where scientists, data managers, and computer science experts discussed "Web Services for Interoperable Ocean Science." The browser's status bar at the bottom shows the time as 1:39 PM and includes several open tabs: "Inbox f...", "Proble...", "Micros...", "Ocean...", "MyWH...", "Sensor...", and "OGC W...".

**Summary**

The Oceans Science Interoperability Experiment will consolidate a portion of the Ocean-Observing community on its understanding of various OGC specifications, solidify demonstrations for Ocean Science application areas, harden software implementations, and produce a candidate OGC Best Practices document that can be used to inform the broader ocean-observing community. To achieve these goals, the Oceans IE will engage the OGC membership to assure that any community recommendations coming from the Oceans group will properly leverage the OGC specifications. Potentially, Change Requests on OGC Specification will be provided to the OGC Technical Committee to influence the underlying specifications. It is not anticipated that this IE will develop any new specifications.

**Initiator Organizations**

The OGC members that are acting as initiators of the Interoperability Experiment are:

- Southeastern Universities Research Association (SURA)
- Texas A&M University Academy for Advanced Telecommunications (TAMU)
- National Center for Atmospheric Research (NCAR)
- The Monterey Bay Aquarium Research Institute (MBARI)
- Gulf of Maine Ocean Observing System (GoMOOS)

**Description**

The Ocean IE will advance several areas of understanding and application of OGC specifications in to web services for interoperable ocean science. The IE will apply existing specifications in the context of an Ocean Science scientific domain. The IE will refine and inform specs, rather than develop new specs. The GALEON IE is a good example in applying WCS access to Atmospheric data.

The Ocean IE will focus on these areas:

- Web Services for Interoperable Ocean Science.
- OGC WMS and WFS access to ocean data, focusing on SOAP bindings.
- Application of the OGC Service Oriented Architecture (SOA) for Web Services to Ocean-observing applications.
- Sensor Web Enablement (SWE) in particular Observations & Measurements and SensorML.
- Sensor Observation Service (SOS) for raw observations.
- GML application schema for Ocean data semantic interoperability using RDF-based ontologies.
- Develop an end-to-end demonstration of web services increasing the interoperability of various regional real-time, ocean-observing programs.

A desired outcome from an interoperability experiment is some kind of "Best Practices" document for the use of OGC adopted spec by a community of interest. The report will be posted as an OGC pending document for consideration by the OGC Specification Program, i.e., the OGC consensus process. This kind of "Best Practice" document would show how to use an OGC spec in specific applications.

**Background**

The Southeastern Universities Research Association (SURA) hosted a workshop in Baltimore October 2005 called OOS Tech 2005 (note: OOS = Ocean Observing System). The workshop included approximately 100 ocean scientists, data managers and computer science experts from around the country. They learned and talked about "Web Services for Interoperable Ocean Science." After the workshop, a subset of the group agreed to work together on a follow-on activity to implement some of what they had learned. The agreed to build from their previous experiences using OGC WMS and WFS specifications. In previous years, they had built some basic elements of a Service Oriented Architecture (SOA) demo at [www.openioos.org](http://www.openioos.org). The OOS Tech 2005 follow-on activity began with 5 loosely defined goals:

 Partners

 [New user?](#)

[More news...](#)

## Office of Naval Research

# OOSTETHYS

OpenIOOS.org | OOSTethys SOS Demo - Mozilla Firefox

File Edit View Go Bookmarks Tools Help

← → ↺ ×

http://www.openioos.org/testbed/sos/gm\_sos.html

Getting Started Latest Headlines

OpenIOOS.org ...where standards enable innovation

Home | FAQ | Disclaimer | Project Wiki

Real-time Maps

Sea Surface Temp

Water-level Models

Wave Models

SOS Salinity

Hurricane Animations

Katrina (2005)

Rita (2005)

Data Providers

AOOS

GoMOOS

MBARI

MVCO

NANOOS



SEACOS

TABS TAMU

UNH Marine Program

VIMS

This site funded by



Site Contributors

NOAA (Hurricane Center)

NOAA (Ocean Service)

NOAA (Data Buoy Center)

NOAA (Coastal Services)

NOAA (AOML)

USGS (Winds)

USGS (Waterwatch)

NASA (Satellites)

NASA (JPL)

Navy (ONR/CBLAST)

GoMOOS

SEACOS

NYHOS

UNC-Chapel Hill

Texas A & M Mesonet

TCOON

VIMS

This interoperability demonstration represents an effort to develop a Web Services Architecture for Ocean Observing. We are seeking participants who would like to serve their in-situ sensors on the [OOSTethys site](#).

SOS Realtime Google Map

130 Sensors reporting

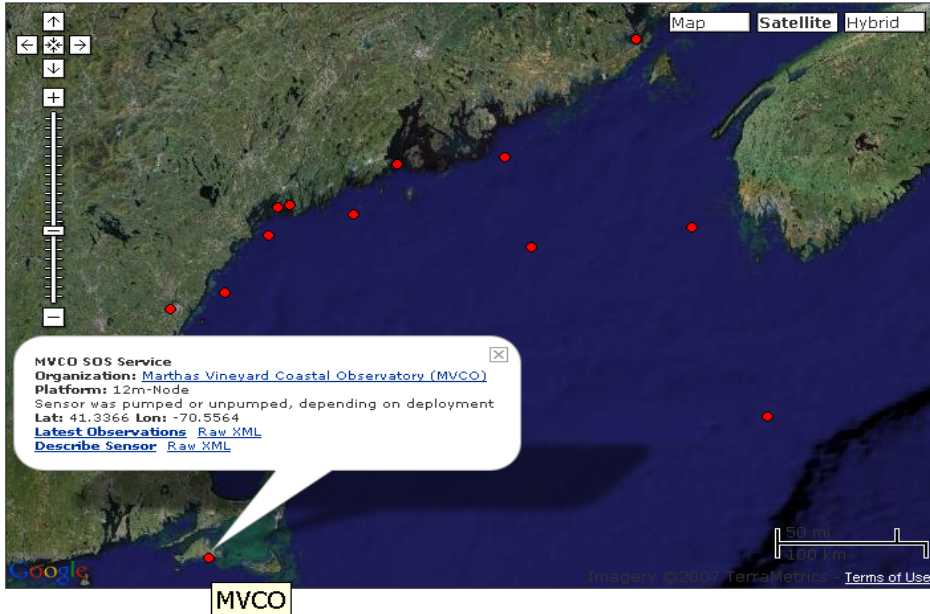
Salinity

Map Satellite Hybrid

Zoom To:  
- select -

Organizations:  
- All -

[OOSTethys SOS Registry Services](#)



MVCO SOS Service

Organization: [Marthas Vineyard Coastal Observatory \(MVCO\)](#)

Platform: 12m-Node

Sensor was pumped or unpumped, depending on deployment

Lat: 41.3366 Lon: -70.5564

[Latest Observations](#) [Raw XML](#)

[Describe Sensor](#) [Raw XML](#)

MVCO

Google

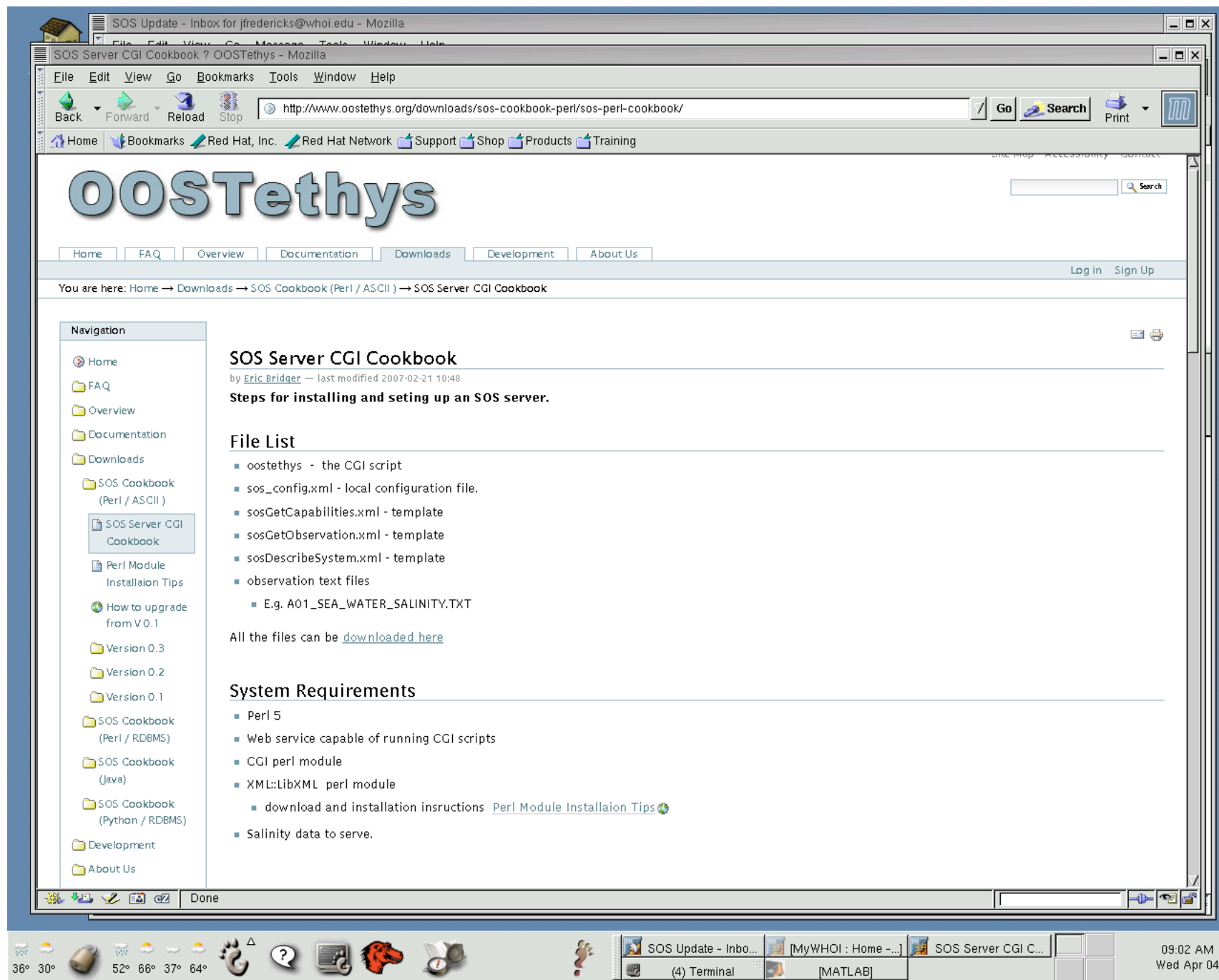
Imagery

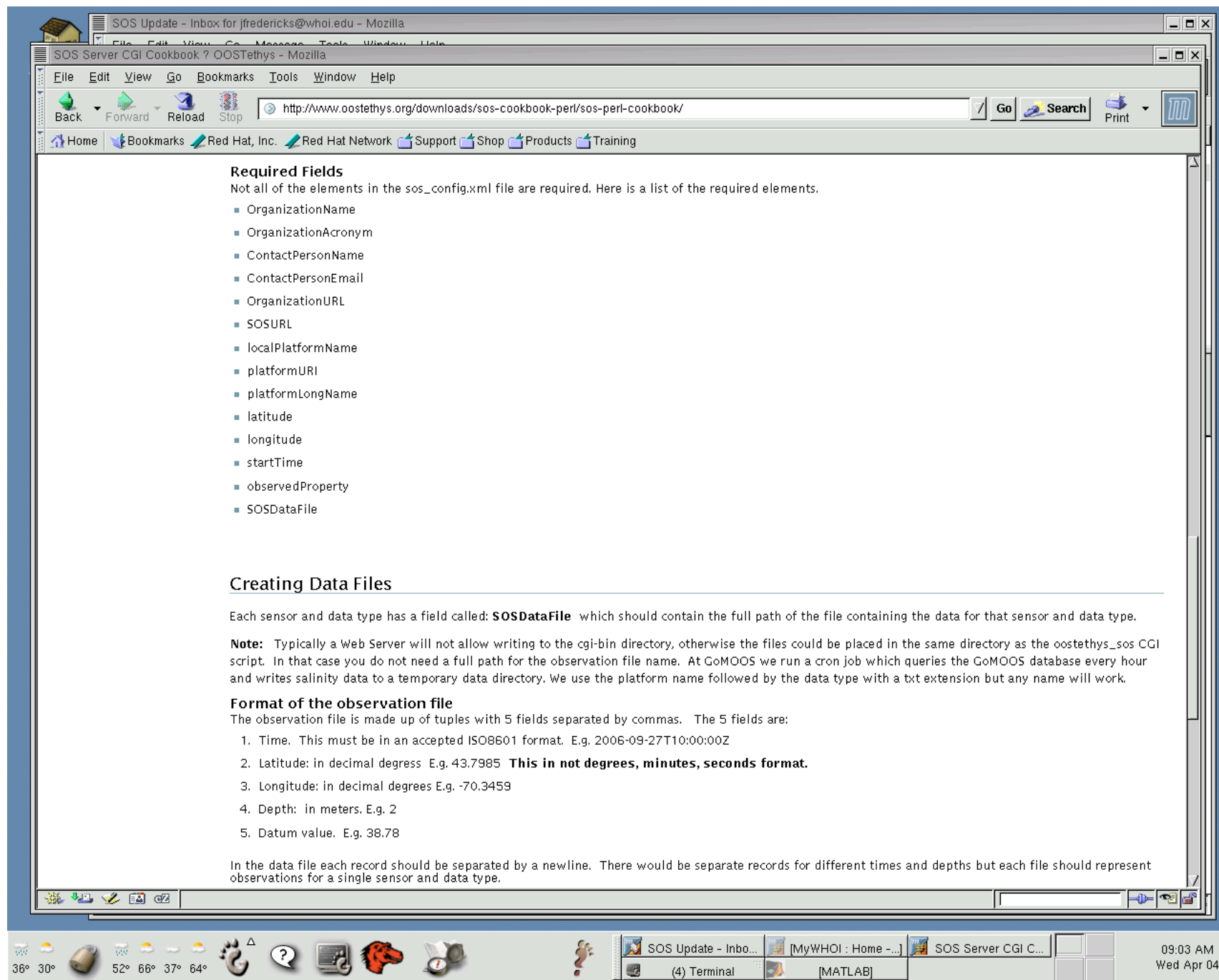
Map

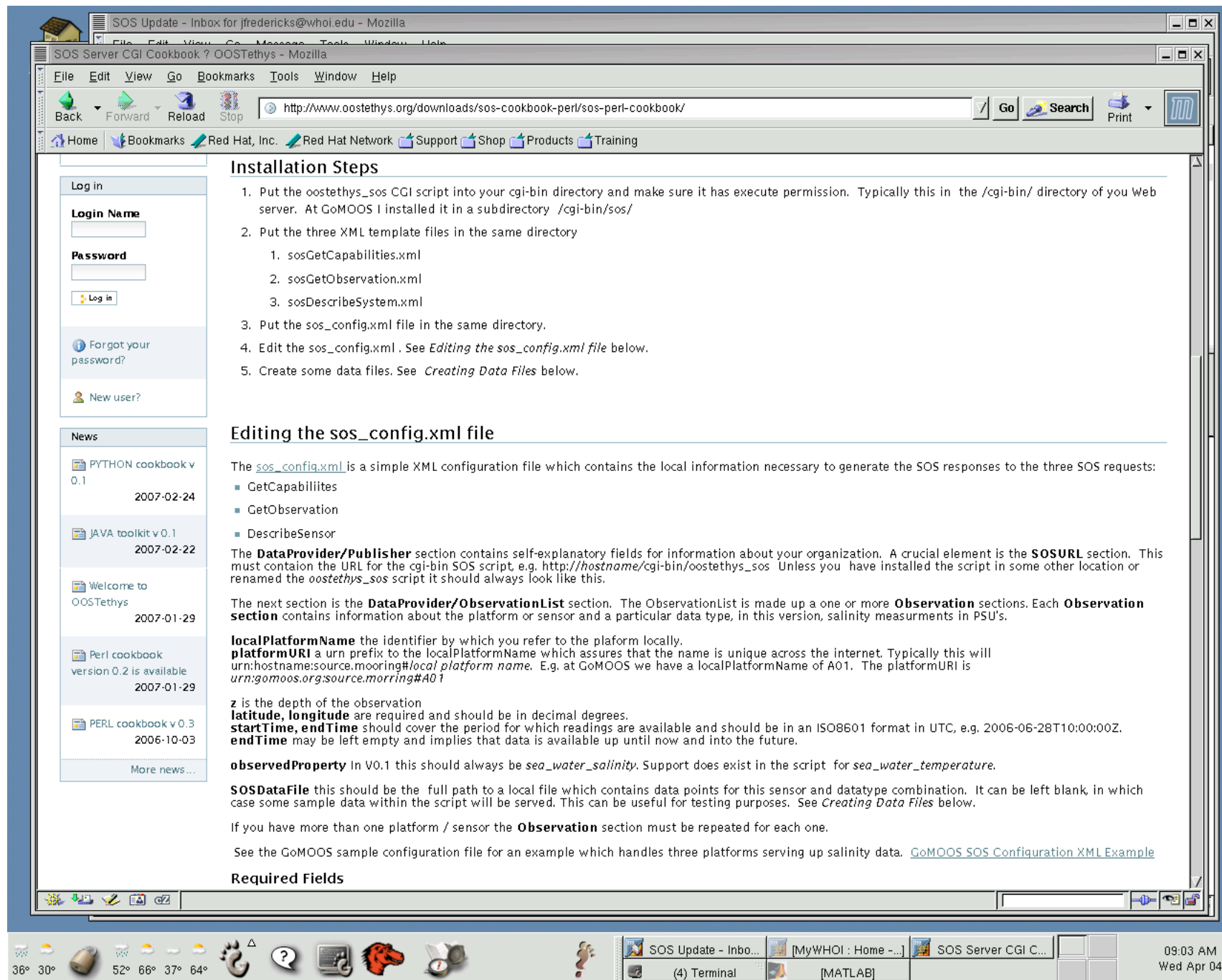
Terms of Use

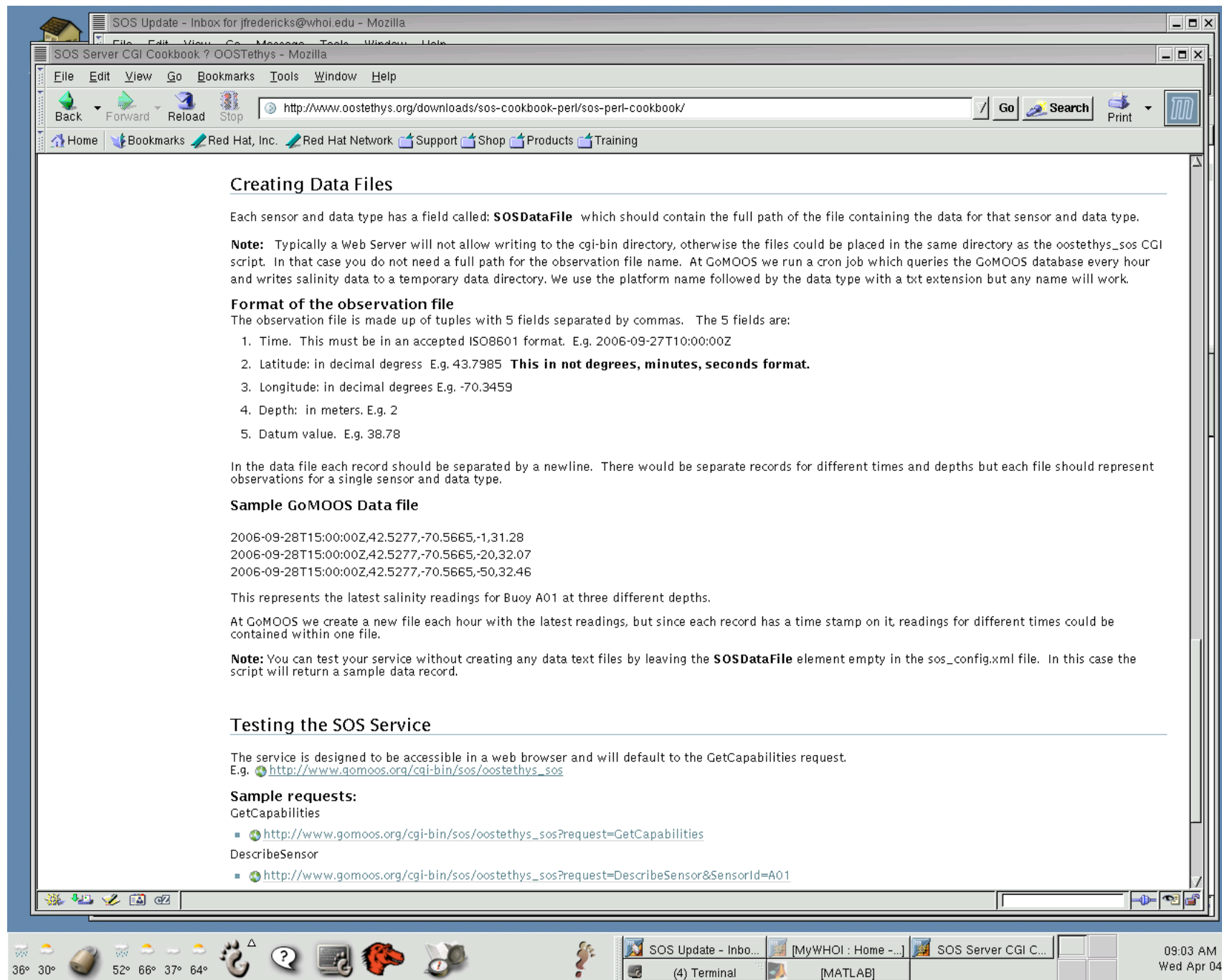
[OOSTethys](#)

Programming, database and user interface design by [GoMOOS](#)









**Mozilla Firefox**

File Edit View Go Bookmarks Tools Help

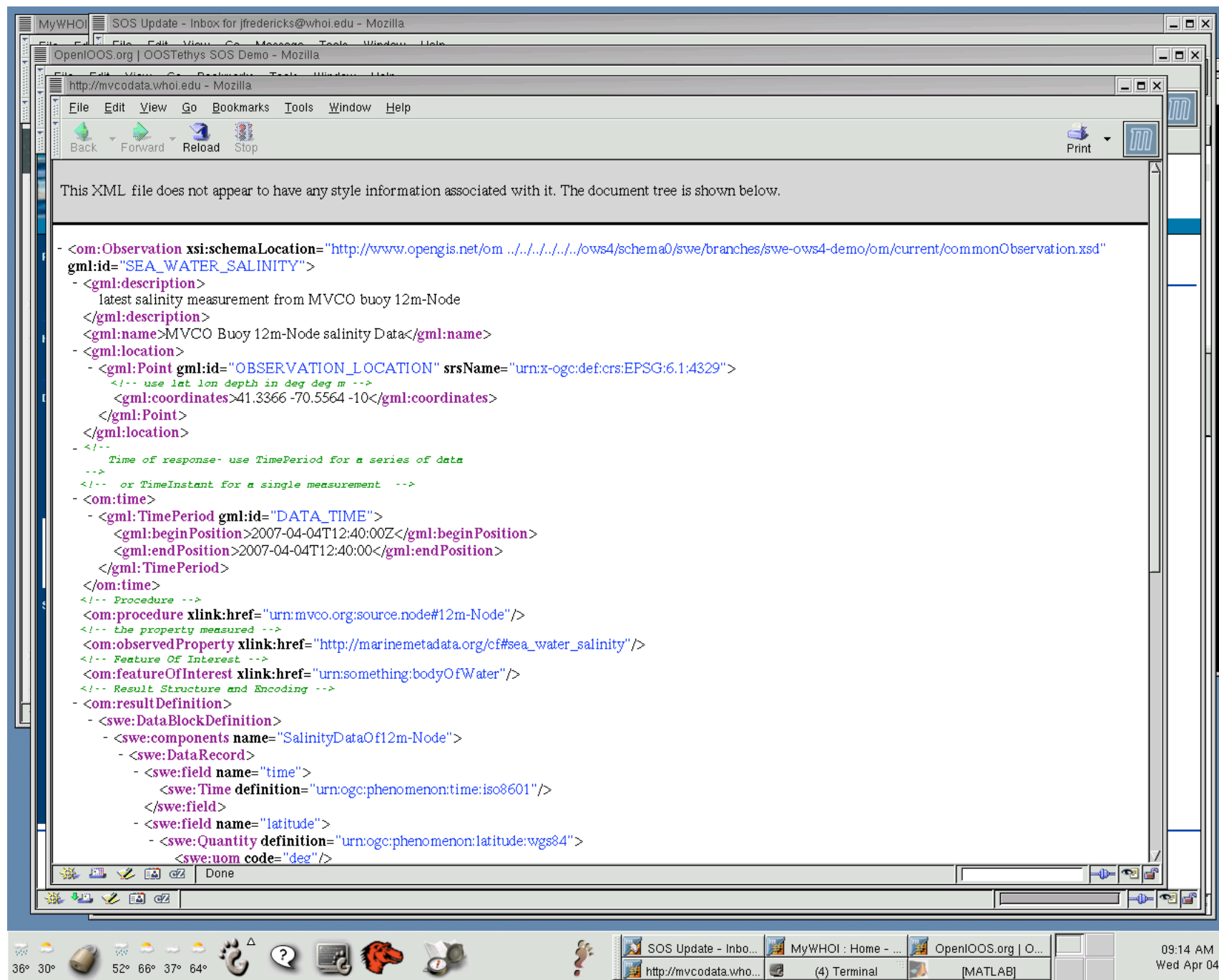
http://mvcodata.who.who.edu/cgi-bin/sos/oostethys\_sos?request=DescribeSensor&SensorId=urn%3Amyco.org%3Asource.node%2312

Getting Started Latest Headlines

http://m...12m-Node VAST - Implementations

This XML file does not appear to have any style information associated with it. The document tree is shown below.

```
- <SensorML xsi:schemaLocation="http://www.opengis.net/sensorML/0 ../ogc/swe/branches/swe-ows4-demo/sensorML/current/base/sensorML.xsd" version="1.0">
- <member>
- <System gml:id="12m-Node">
- <gml:description>
  Sensor was pumped or unpumped, depending on deployment
</gml:description>
- <keywords>
- <KeywordList codeSpace="http://gcmd.nasa.gov/Resources/valids/keyword_list.html">
  <keyword>OCEANOGRAPHY</keyword>
</KeywordList>
</keywords>
- <identification>
- <IdentifierList>
- <identifier>
- <Term>
  <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:longName"/>
  <value>12m Node at MVCO</value>
</Term>
</identifier>
- <identifier>
- <Term>
  <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:shortName"/>
  <value>12m-Node</value>
</Term>
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- <identifier>
- <Term>
  <swe:codeSpace xlink:href="http://www.w3.org/1999/02/22-rdf-syntax-ns#ID"/>
  <value>urn:myco.org:source.node#12m-Node</value>
</Term>
</identifier>
</IdentifierList>
```



MyWHOI | SOS Update - Inbox for jfredericks@whoi.edu - Mozilla

OpenIOOS.org | OOSTethys SOS Demo - Mozilla

http://mvcodata.whoi.edu - Mozilla

File Edit View Go Bookmarks Tools Window Help

Back Forward Reload Stop

Print

This XML file does not appear to have any style information associated with it. The document tree is shown below.

```
- <SensorML xsi:schemaLocation="http://www.opengis.net/sensorML/0 ../ogc/swe/branches/swe-ows4-demo/sensorML/current/base/sensorML.xsd" version="1.0">
- <member>
- <System gml:id="12m-Node">
- <gml:description>
  Sensor was pumped or unpumped, depending on deployment
</gml:description>
- <keywords>
- <KeywordList codeSpace="http://gcmd.nasa.gov/Resources/valids/keyword_list.html">
  <keyword>OCEANOGRAPHY</keyword>
</KeywordList>
</keywords>
- <identification>
- <IdentifierList>
- <identifier>
- <Term>
  <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:longName"/>
  <value>12m Node at MVC0</value>
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- <identifier>
- <Term>
  <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:shortName"/>
  <value>12m-Node</value>
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- <Term>
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</Term>
</identifier>
</IdentifierList>
</identification>
- <classification>
- <ClassifierList>
- <classifier>
- <Term>
  <swe:codeSpace xlink:href="urn:mmi.org:platform"/>
```

Done

36° 30° 52° 66° 37° 64°

SOS Update - Inbo... MyWHOI : Home - ... OpenIOOS.org | O...  
http://mvcodata.who... (4) Terminal [MATLAB]

09:14 AM Wed Apr 04



Mozilla

File Edit View Go Bookmarks Tools Window Help

Back Forward Reload Stop [http://mvcodata.whoi.edu/cgi-bin/sos/postethys\\_sos?request=DescribeSensor&SensorId=urn%3Amvco.org%3Asource.node%2312](http://mvcodata.whoi.edu/cgi-bin/sos/postethys_sos?request=DescribeSensor&SensorId=urn%3Amvco.org%3Asource.node%2312) Go Search Print

Home Bookmarks Red Hat, Inc. Red Hat Network Support Shop Products Training

This XML file does not appear to have any style information associated with it. The document tree is shown below.

```
<SensorML xsi:schemaLocation="http://www.opengis.net/sensorML/0 ../ogc/swe/branches/swe-ows4-demo/sensorML/current/base/sensorML.xsd" version="1.0">
  <member>
    <System gml:id="12m-Node">
      <gml:description>
        Sensor was pumped or unpumped, depending on deployment
      </gml:description>
      <keywords>
        <KeywordList codeSpace="http://gcmd.nasa.gov/Resources/valids/keyword_list.html">
          <keyword>OCEANOGRAPHY</keyword>
        </KeywordList>
      </keywords>
      <identification>
        <IdentifierList>
          <identifier>
            <Term>
              <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:longName"/>
              <value>12m Node at MVCO</value>
            </Term>
          </identifier>
          <identifier>
            <Term>
              <swe:codeSpace xlink:href="urn:x-ogc:def:identifier:OGC:shortName"/>
              <value>12m-Node</value>
            </Term>
          </identifier>
          <identifier>
            <Term>
              <swe:codeSpace xlink:href="http://www.w3.org/1999/02/22-rdf-syntax-ns#ID"/>
              <value>urn:mvcodata.org:source.node#12m-Node</value>
            </Term>
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      <classification>
        <ClassifierList>
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              <swe:codeSpace xlink:href="urn:mml:org:platform"/>
              <value/>
            </Term>
          </classifier>
        </ClassifierList>
      </classification>
    </System>
  </member>
</SensorML>
```

Done

36° 30° 52° 70° 39° 64° Re: SOS pilot for M... Mozilla http://mvcodata.who... (4) Terminal [MATLAB] 09:21 AM Wed Apr 04

The screenshot displays a web browser window titled "OpenIROS.org | OOSTethys SOS Demo - Mozilla". The main content area shows a "12m-Node" profile. The profile includes a description, location, contact information, and keywords. A sidebar on the left lists various data sources. A map view shows the location of the node on the coast of Massachusetts. The bottom status bar shows the system clock as 09:14 AM on Wed Apr 04.

<b>Description:</b>	Sensor was pumped or unpumped, depending on deployment
<b>Marthas Vineyard Coastal Observatory</b>	<a href="http://www.whoi.edu/mvco">http://www.whoi.edu/mvco</a>
<b>Janet Fredericks</b>	<a href="mailto:jfredericks@whoi.edu">jfredericks@whoi.edu</a>
<b>Keywords from <a href="http://gcmd.nasa.gov/Resources/valids/keyword_list.html">http://gcmd.nasa.gov/Resources/valids/keyword_list.html</a></b>	
OCEANOGRAPHY	
<b>longName</b>	12m Node at MVCO
<b>shortName</b>	12m-Node
<b>rdf-syntax-ns#ID</b>	urn:mvco.org:source.node#12m-Node
<b>Valid begin time:</b>	2002-04-19T21:20:00Z
<b>Valid end time:</b>	now
<b>SYSTEM_LOCATION Point:</b>	41.3366 -70.5564 EPSG:6.1:4329
<b>Outputs:</b>	SalinityDataOf12m-Node

Close

NOAA (Coastal Services)  
 NOAA (ADML)  
 USGS (Winds)  
 USGS (Waterwatch)  
 NASA (Satellites)  
 NASA (JPL)  
 Navy (ONR/CBLAST)  
 GoMOOS  
 SEACDOS  
 NYHOS  
 UNC-Chapel Hill  
 Texas A & M Mesonet  
 TCOON  
 VIMS

Sensor was pumped or unpumped, depending on deployment  
 Lat: 41.3366 Lon: -70.5564  
[Latest Observations](#) [Raw XML](#)  
[Describe Sensor](#) [Raw XML](#)

Map Satellite Hybrid Zoom To: - select -  
 Organizations: - All -  
[OOSTethys SOS Registry Services](#)

OOSTethys  
 Programming, database and user interface design by GoMOOS

09:14 AM Wed Apr 04



## Important Future Initiatives?

**QA/QC into SensorML: data dictionaries;  
setting them up in SensorML profiles;  
providing tutorials for implementation  
and demonstrating by integration into  
oostethys\_sos**

# <http://q2o.whoi.edu> Funded 3 yrs



# Semantic Interoperability

- Domain experts define best practices and required vocabularities – working with IT experts to keep Interoperability goal in mind and guide in developing relationships for RDF definitions (Eg, <http://qartod.org>)
- Build buy-in within and across communities to promote interdisciplinary potential (Eg, <http://marinemetadata.org>)